

Proof-Nets and λ -calculus

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Ecole Polytechnique, LIX

- 1 Introduction
 - General motivations
 - MELL Proof-Nets and Girard's translation
 - Proof-Nets
- 2 Bisimulation
 - Statics
 - Dynamics
- 3 The structural λ -calculus (Accattoli, Kesner)
- 4 Properties

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Proof-Nets

Visual and parallel syntax

Difficult to manage formally

Non-inductive characterizations

Explicit name identification

Nameless

Terms

Understood by everyone

Easy inductive reasoning

Too rigid tree structure

Name identification for free

α -equivalence

Goal: take the best of the two worlds!

PN perspective: an algebraic language

- PN are as *nice to see* as *dreadful to manage*.
- Limited to a *tiny community*.
- *Idea*: try to find an *elegant* algebraic language for PN.
- *Graphical intuitions* \Rightarrow *algebraic theorems*.
- *First Aim*: to increase the *proving power* of the PN-specialist.
- *Second Aim*: PN technology to a *wider community*.
- *Third Aim*: to work with PN and write *graph-free papers*!

Term perspective: a syntactic model

- λ -calculus Proof-Nets are related to **explicit substitutions** (ES).
- **No canonical ES-calculus** despite 20 years of research.
- **Problem: too much freedom** in designing the rules.
- **In PN**: correctness and parallelism **limit** the possible choices.
- **Idea**: re-design ES using PN as **syntactic model**.

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Multiplicative Exponential Linear Logic (MELL)

Identity rules:

$$\frac{}{\vdash A^\perp, A} \text{ax}$$

$$\frac{\vdash \Gamma, A \quad \vdash A^\perp, \Delta}{\vdash \Gamma, \Delta} \text{cut}$$

Multiplicative rules:

$$\frac{\vdash \Gamma, A \quad \vdash \Delta, B}{\vdash \Gamma, \Delta, A \otimes B} \otimes$$

$$\frac{\vdash \Gamma, A, B}{\vdash \Gamma, A \wp B} \wp$$

Exponential rules:

$$\frac{\vdash \Gamma, A}{\vdash \Gamma, ?A} ?d$$

$$\frac{\vdash ?\Gamma, A}{\vdash ?\Gamma, !A} !$$

$$\frac{\vdash \Gamma, ?A, ?A}{\vdash \Gamma, ?A} ?c$$

$$\frac{\vdash \Gamma}{\vdash \Gamma, ?A} ?w$$

λ -calculus actually requires a **tiny intuitionistic fragment** of MELL.

Identity group:

$$\frac{}{\vdash A^\perp, A} \text{ax}$$

$$\frac{\vdash \Gamma, A \quad \vdash A^\perp, \Delta}{\vdash \Gamma, \Delta} \text{cut}$$

Linear implication:

$$\frac{\Gamma \vdash A \quad \Delta, B \vdash C}{\Gamma, \Delta, A \multimap B \vdash C} \multimap_L$$

$$\frac{\Gamma, A \vdash B}{\Gamma \vdash A \multimap B} \multimap_R$$

Exponentials:

$$\frac{\Gamma, A \vdash B}{\Gamma, !A \vdash B} ?d$$

$$\frac{! \Gamma \vdash A}{! \Gamma \vdash !A} !$$

$$\frac{\Gamma, !A, !A \vdash B}{\Gamma, !A \vdash B} ?c$$

$$\frac{\Gamma \vdash B}{\Gamma, !A \vdash B} ?w$$

Girard's translation in sequent calculus

Formulas: $X^\circ = X$ and $(A \rightarrow B)^\circ = (!A^\circ) \multimap B^\circ$

Sequents: $(\Gamma \vdash A)^\circ = !\Gamma^\circ \vdash A^\circ$

Proofs:

$$\frac{}{A \vdash A} \text{ax} \quad \rightarrow \quad \frac{}{A^\circ \vdash A^\circ} \text{ax} \quad \frac{}{!A^\circ \vdash A^\circ} ?d$$

$$\frac{\Gamma, A \vdash B}{\Gamma \vdash A \Rightarrow B} \Rightarrow_I \quad \rightarrow \quad \frac{!\Gamma^\circ, !A^\circ \vdash B^\circ}{!\Gamma^\circ \vdash !A^\circ \multimap B^\circ} \multimap_R$$

$$\frac{\Gamma \vdash A \Rightarrow B \quad \Gamma \vdash A}{\Gamma \vdash B} \Rightarrow_E \quad \rightarrow \quad \frac{\frac{!\Gamma^\circ \vdash A^\circ}{!\Gamma^\circ \vdash !A^\circ} ! \quad \frac{}{B^\circ \vdash B^\circ} \text{ax}}{!\Gamma^\circ \vdash !A^\circ \multimap B^\circ \vdash B^\circ} \multimap_L \quad \frac{}{!\Gamma \vdash B} \text{cut}$$

Remark: every \Rightarrow_E introduces a **cut**.

Untyped λ -calculus requires a **recursive** type $o = !o \multimap o = ?o \wp o$.

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MELL Proof-Nets 1: multiplicatives

$$\left(\overline{\vdash A^\perp, A} \text{ ax} \right)^* = \text{ax}$$

$$\left(\frac{\begin{array}{c} \cdot \\ \vdots \\ \pi \\ \vdots \\ \cdot \end{array} \quad \begin{array}{c} \cdot \\ \vdots \\ \theta \\ \vdots \\ \cdot \end{array}}{\vdash \Gamma, A \quad \vdash A^\perp, \Delta} \text{ cut} \right)^* = \text{cut}$$

$$\left(\frac{\begin{array}{c} \cdot \\ \vdots \\ \pi \\ \vdots \\ \cdot \end{array} \quad \begin{array}{c} \cdot \\ \vdots \\ \theta \\ \vdots \\ \cdot \end{array}}{\vdash \Gamma, A \quad \vdash \Delta, B} \otimes \right)^* = \otimes$$

$$\left(\frac{\begin{array}{c} \cdot \\ \vdots \\ \pi \\ \vdots \\ \cdot \end{array}}{\vdash \Gamma, A, B} \wp \right)^* = \wp$$

MELL Proof-Nets 2: exponentials

$$\left(\frac{\begin{array}{c} \cdot \\ \pi \\ \cdot \\ \cdot \end{array}}{\frac{\vdash \Gamma}{\vdash \Gamma, ?A} w} \right)^* = \begin{array}{c} \textcircled{\pi^*} \\ \swarrow \quad \searrow \\ \cdot \quad \cdot \\ \Gamma \quad ?A \end{array} \begin{array}{c} W \\ \downarrow \\ \cdot \\ ?A \end{array}$$

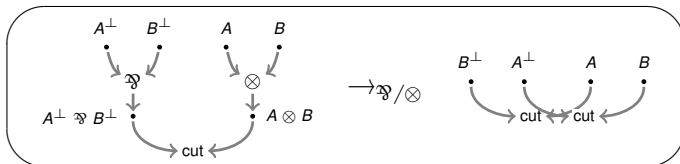
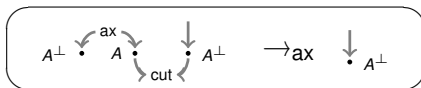
$$\left(\frac{\begin{array}{c} \cdot \\ \pi \\ \cdot \\ \cdot \end{array}}{\frac{\vdash \Gamma, A}{\vdash \Gamma, ?A} ?d} \right)^* = \begin{array}{c} \textcircled{\pi^*} \\ \swarrow \quad \searrow \\ \cdot \quad \cdot \\ \Gamma \quad A \end{array} \begin{array}{c} \cdot \\ \downarrow \\ ?d \\ \cdot \\ ?A \end{array}$$

MELL Proof-Nets 2: exponentials

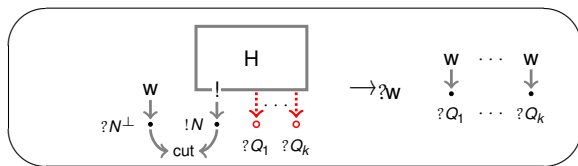
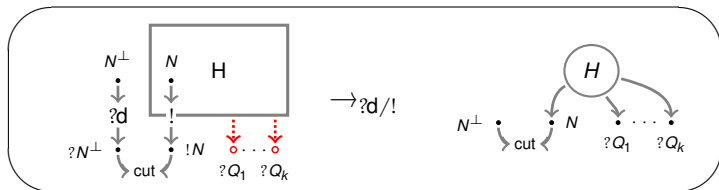
$$\left(\frac{\begin{array}{c} \cdot \\ \pi \\ \cdot \\ \cdot \end{array}}{\frac{\vdash ?\Gamma, A}{\vdash ?\Gamma, !A} !} \right)^* = \text{Diagram}$$

$$\left(\frac{\begin{array}{c} \cdot \\ \pi \\ \cdot \\ \cdot \end{array}}{\frac{\vdash \Gamma, ?A, ?A}{\vdash \Gamma, ?A} ?C} \right)^* = \text{Diagram}$$

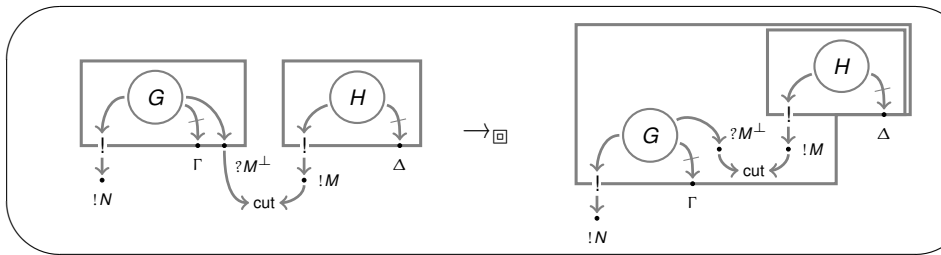
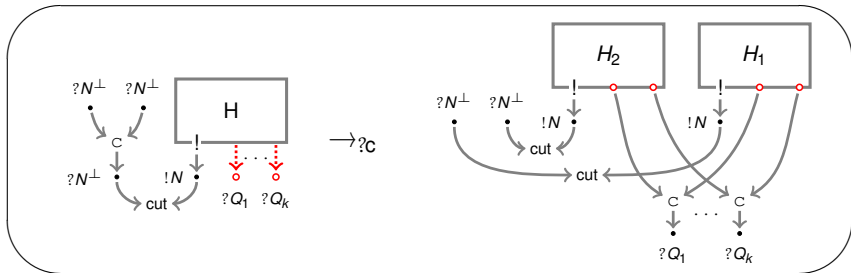
Multiplicative rules



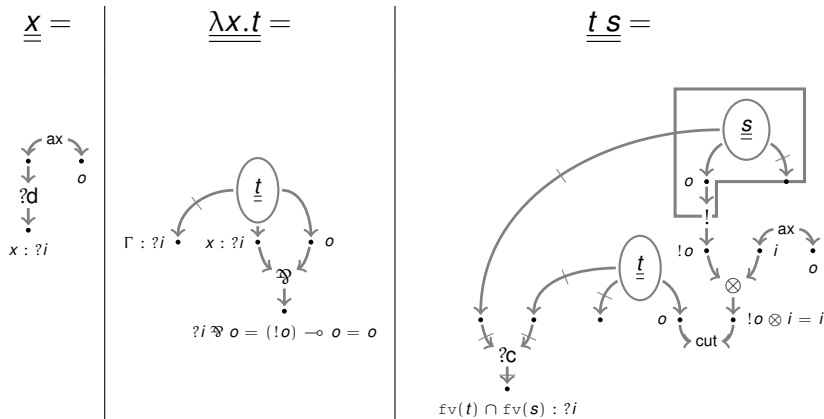
Exponential rules 1



Exponential rules 1



Girard's translation on Proof-Nets



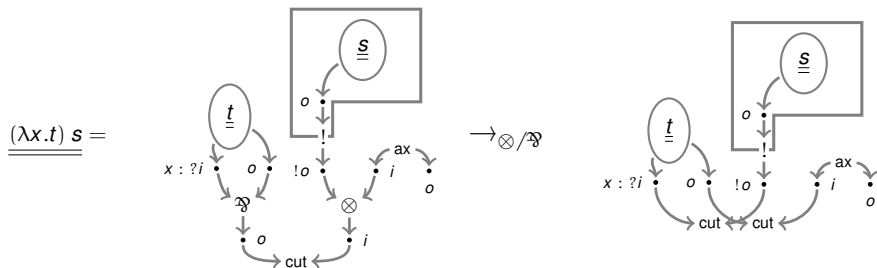
The translation of $t = (x y) z$ **has an axiom cut** while t is **normal**.

Remark: the translation of a term can only have **multiplicative cuts**.

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A more relevant mismatch

Let's reduce a *graphical β -redex*:



We get a net with an *exponential cut*, i.e. *not a λ -term*.

The further elimination of the exponential cut gets a λ -term.

Simulation of λ -calculus in PN

The **operational relation** between terms and graphs is as follows:

$$\begin{array}{ccc} t & \rightarrow_{\beta} & t' \\ \downarrow_{\cdot} & & \downarrow_{\cdot} \\ G_t & \rightarrow^+ & G_{t'} \end{array}$$

In the other sense:

$$G_t \rightarrow G' \Rightarrow \begin{array}{ccccc} t & & \rightarrow & & t' \\ \downarrow_{\cdot} & & & & \downarrow_{\cdot} \\ G_t & \rightarrow & G' & \rightarrow^* & G_{t'} \end{array}$$

To simplify we want to represent the **intermediary steps** on terms.

Diagrammatically we want:

$$\begin{array}{c} t \\ \downarrow\!:- \\ G_t \end{array} \rightarrow G' \quad \Rightarrow \quad \exists t' \text{ s.t.} \quad \begin{array}{c} t \rightarrow t' \\ \downarrow\!:- \quad \downarrow\!:- \\ G_t \rightarrow G' \end{array}$$

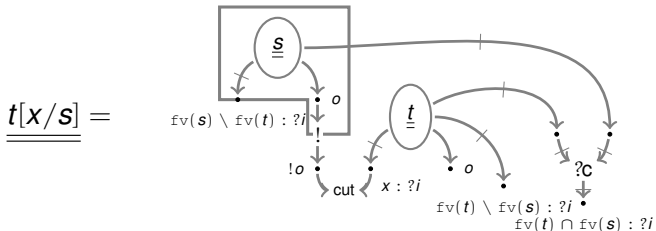
And

$$\begin{array}{c} t \rightarrow t' \\ \downarrow\!:- \\ G_t \end{array} \quad \Rightarrow \quad \exists G' \text{ s.t.} \quad \begin{array}{c} t \rightarrow t' \\ \downarrow\!:- \quad \downarrow\!:- \\ G_t \rightarrow G' \end{array}$$

We want the translation to be a **strong bisimulation**.

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Let's introduce **explicit substitutions** $t[x/s]$:



Now **any graph** can be mapped to a **term**.

Various technical issues

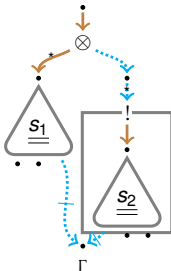
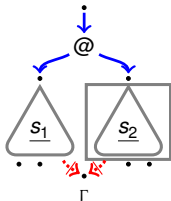
- It is necessary to work *modulo axiom cuts*.
⇒ *We collapse axioms and cuts*.
- *Variable representation* presents some other technical issues:
 - Associativity and commutativity of contractions.
 - Permutation of contractions and weakenings with promotions.
 - On the fly removal of contractions with weakenings⇒ *We collapse contractions*.
- Moreover, here we use PN to understand terms:
⇒ *We draw PN as syntax trees of terms*.

\underline{x}

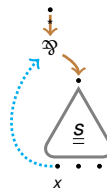
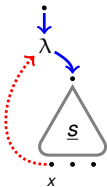
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 $\begin{array}{c} \bullet \\ \vdots \\ \text{V} \\ \vdots \\ \bullet \\ x \end{array}$
 $\begin{array}{c} \bullet \\ \vdots \\ \text{?d} \\ \vdots \\ \bullet \\ x \end{array}$
 $\underline{s_1} \ \underline{s_2}$

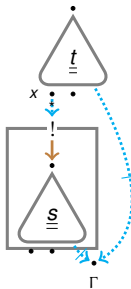
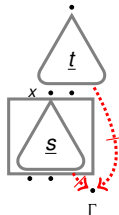
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 $\underline{\lambda x.s}$

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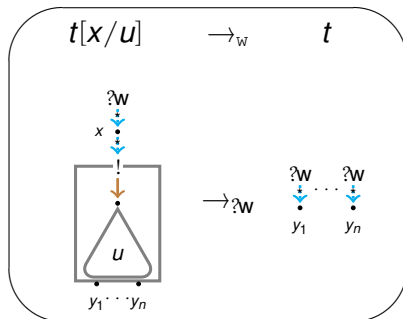
 $\underline{t[x/s]}$

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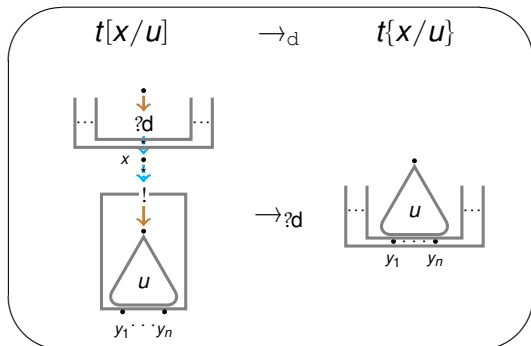
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Garbage Collection



If $x \notin \text{fv}(t)$ then $t[x/u]$ as a cut **as this one**.
 Thus it reduces to t , since u is **simply erased**.

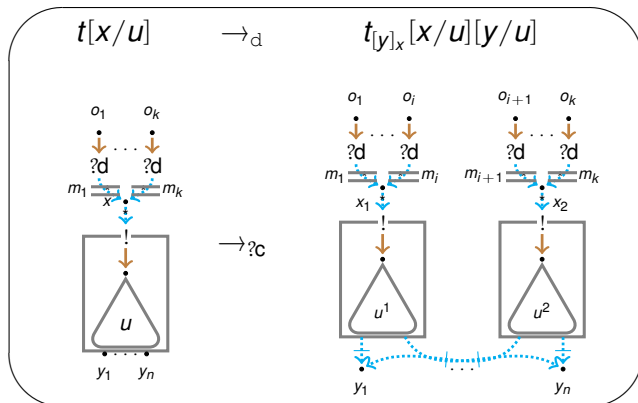
Linear Substitution



If $x \in \text{fv}(t)$ and $|t|_x = 1$ then x is **replaced** by u .

Remark: reduction **through** box borders.

Duplication

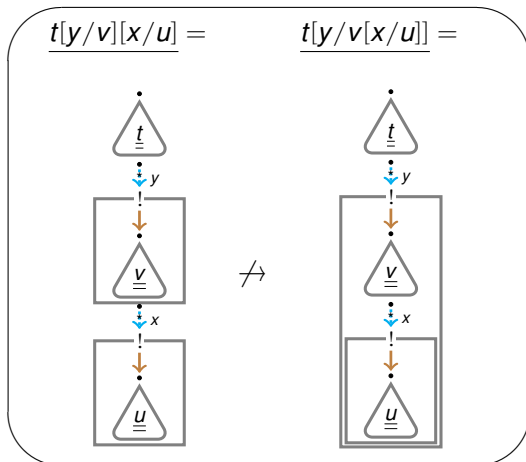


If $x \in \text{fv}(t)$ and $|t|_x > 1$ then **some occurrences** of x give rise to a **new variable**, substituted by a copy of u .

No commutative cut!

Main feature: no commutative cut!

This rule **is not** part of the operational semantics:



Minimal LJ

Big-steps cut-elimination



λ -calculus

β -reduction.

Minimal LJ

Small-steps cut-elimination

With commutative reductions



λ -calculus

With Explicit Substitutions

Minimal LJ

Small-steps cut-elimination.

Without commutative reductions



Structural λ -calculus λ_j

\simeq

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Structure vs Multiplicity

Traditionally, ES are introduced as follows:

$$(\lambda x.t) u \rightarrow_B t[x/u]$$

Rules act by induction on the **structure** of terms by **proximity**.

$$x[x/u] \rightarrow u$$

$$y[x/u] \rightarrow y$$

$$(\lambda y.t)[x/u] \rightarrow \lambda y.t[x/u]$$

$$(t v)[x/u] \rightarrow t[x/u] v[x/u]$$

$$t[y/v][x/u] \rightarrow t[x/u][y/v[x/u]]$$

Structure vs Multiplicity

The λ_j -calculus acts by induction on *multiplicities* at a *distance*.

$$t[x/u] \rightarrow \dots \quad \text{if } |t|_x = 0$$

$$t[x/u] \rightarrow \dots \quad \text{if } |t|_x = 1$$

$$t[x/u] \rightarrow \dots \quad \text{if } |t|_x > 1$$

Modular: new constructors do not need new rules!

- Rule **at a distance**:

$$(\lambda x.t)[\cdot/\cdot] \dots [\cdot/\cdot] u \rightarrow_{B\text{-distance}} t[x/u][\cdot/\cdot] \dots [\cdot/\cdot]$$

- Traditionally a configuration like:

$$(\lambda x.t)[y/v] u$$

is not a redex, as it is **blocked** by $[y/v]$.

- In λ_j , instead, **it is a redex**.

- ES rules by induction on **multiplicities**:

$$(\lambda x.t)L u \rightarrow_{\text{B-distance}} t[x/u]L$$

$$t[x/u] \rightarrow_{\text{weakening}} t \quad |t|_x = 0$$

$$t[x/u] \rightarrow_{\text{dereliction}} t\{x/u\} \quad |t|_x = 1$$

$$t[x/u] \rightarrow_{\text{contraction}} t_{[y]_x}[x/u][y/u] \quad |t|_x > 1 \text{ \& } y \text{ fresh}$$

Distance on terms = **Locality on graphs**.

Example

$((\lambda z. (\lambda x. x x)) z') y \rightarrow_{\text{B-distance}}$

$(\lambda x. x x)[z/z'] y \rightarrow_{\text{B-distance}}$

$(x x)[x/y][z/z'] \rightarrow_{\text{weakening}}$

$(x x)[x/y] \rightarrow_{\text{contraction}}$

$(x_1 x_2)[x_1/y][x_2/y] \rightarrow_{\text{dereliction}}$

$(y x_2)[x_2/y] \rightarrow_{\text{dereliction}}$

$y y$

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- The translation on graphs induces a quotient:

$$(\lambda y.t)[u/x] \equiv \lambda y.(t[u/x]) \quad \text{if } y \notin \text{fv}(u)$$

$$(t[u/x]) v \equiv (t v)[u/x] \quad \text{if } x \notin \text{fv}(v)$$

$$t[x/u][y/v] \equiv t[y/v][x/u] \quad \text{if } y \notin \text{fv}(u) \ \& \ x \notin \text{fv}(v)$$

- Which is a strong bisimulation by construction:

$$\begin{array}{ccc} t & \rightarrow & t' \\ \downarrow \cdot & & \downarrow \cdot \\ G & \rightarrow & G' \\ \uparrow \cdot & & \uparrow \cdot \\ s & \rightarrow & s' \end{array}$$